

Basis

Basis

Why nonzero?

- Let V be a nonzero subspace of \mathbb{R}^n . A **basis** B for V is a **linearly independent generation set** of V .

$\{\mathbf{e}_1, \mathbf{e}_2, \dots, \mathbf{e}_n\}$ is a basis for \mathbb{R}^n .

1. $\{\mathbf{e}_1, \mathbf{e}_2, \dots, \mathbf{e}_n\}$ is independent
2. $\{\mathbf{e}_1, \mathbf{e}_2, \dots, \mathbf{e}_n\}$ generates \mathbb{R}^n .

$\left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\}$ is a basis for \mathbb{R}^2

$\left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ -1 \end{bmatrix} \right\}$ $\left\{ \begin{bmatrix} 1 \\ 3 \end{bmatrix}, \begin{bmatrix} -3 \\ 1 \end{bmatrix} \right\}$ $\left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \end{bmatrix} \right\}$ any two independent vectors form a basis for \mathbb{R}^2

Basis

- The pivot columns of a matrix form a basis for its columns space.

$$\begin{bmatrix} \boxed{1} & 2 & \boxed{-1} & \boxed{2} & 1 & 2 \\ \boxed{-1} & -2 & \boxed{1} & \boxed{2} & 3 & 6 \\ 2 & 4 & -3 & 2 & 0 & 3 \\ \boxed{-3} & -6 & \boxed{2} & \boxed{0} & 3 & 9 \end{bmatrix} \xrightarrow{\text{RREF}} \begin{bmatrix} \boxed{1} & 2 & \boxed{0} & \boxed{0} & -1 & -5 \\ \boxed{0} & 0 & \boxed{1} & \boxed{0} & 0 & -3 \\ \boxed{0} & 0 & \boxed{0} & \boxed{1} & 1 & 2 \\ \boxed{0} & 0 & \boxed{0} & \boxed{0} & 0 & 0 \end{bmatrix}$$

pivot columns

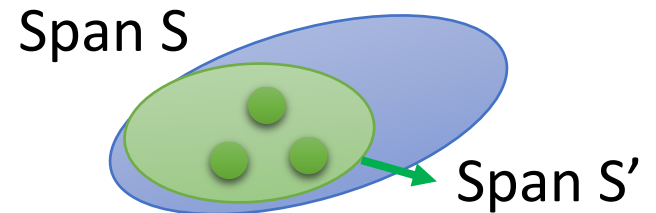
$$\text{Col } A = \text{Span} \left\{ \begin{bmatrix} 1 \\ -1 \\ 2 \\ -3 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \\ -3 \\ 2 \end{bmatrix}, \begin{bmatrix} 2 \\ 2 \\ 2 \\ 0 \end{bmatrix} \right\}$$

Property

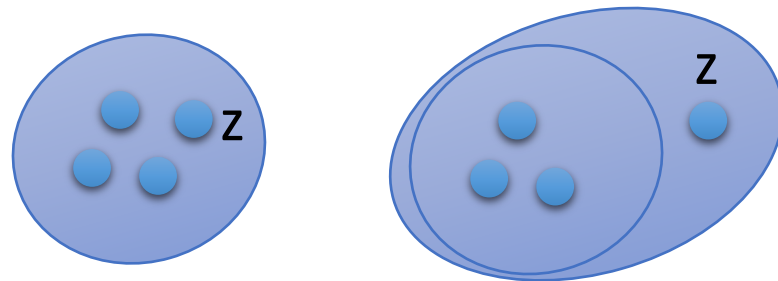
- (a) S is contained in $\text{Span } S$

Basis is always in
its subspace

- (b) If a finite set S' is contained in $\text{Span } S$, then $\text{Span } S'$ is also contained in $\text{Span } S$
 - Because $\text{Span } S$ is a subspace



- (c) For any vector z , $\text{Span } S = \text{Span } S \cup \{z\}$ if and only if z belongs to the $\text{Span } S$



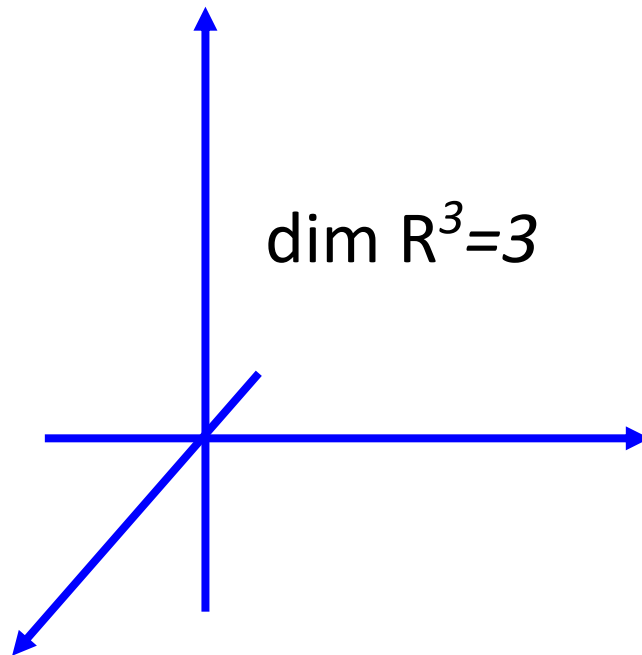
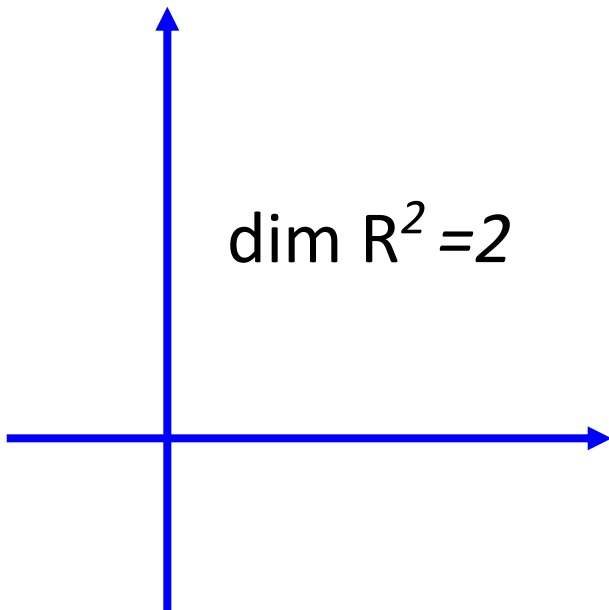
Theorem

- 1. A basis is the **smallest** generation set.
- 2. A basis is the **largest** independent vector set in the subspace.
- 3. Any two bases for a subspace **contain the same number of vectors**.
 - The number of vectors in a basis for a nonzero subspace V is called **dimension** of V ($\dim V$).

Theorem 3

Every basis of \mathbb{R}^n
has n vectors.

- The number of vectors in a basis for a subspace V is called the dimension of V , and is denoted $\dim V$
 - The dimension of zero subspace is 0



Example

$$V = \left\{ \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} \in \mathcal{R}^4 : \begin{array}{l} \cancel{x_1 - 3x_2 + 5x_3 - 6x_4 = 0} \\ x_1 = 3x_2 - 5x_3 + 6x_4 \end{array} \right\} \quad \begin{array}{l} \text{Find dim } V \\ \text{dim } V = 3 \end{array}$$

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 3x_2 - 5x_3 + 6x_4 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix}$$

Basis? Independent vector set that generates V



More from Theorems

Any two bases for a subspace contain the same number of vectors.

\mathbb{R}^m have a basis $\{\mathbf{e}_1, \mathbf{e}_2, \dots, \mathbf{e}_m\}$ All bases have m vectors

$$\dim \mathbb{R}^m = m$$

A basis is the smallest generation set.

A vector set generates \mathbb{R}^m must contain at least m vectors.

Because a basis is the smallest generation set

Any other generation set has at least m vectors.

A basis is the largest independent set in the subspace.

Any independent vector set in \mathbb{R}^m contain at most m vectors.

Independent

All columns are independent




Every column is a pivot column



Every column in RREF(A) is standard vector.

3X4

$$\begin{bmatrix} * & * & * & * \\ * & * & * & * \\ * & * & * & * \end{bmatrix}$$

Columns are linearly independent 

RREF



$$\begin{bmatrix} 1 & 0 & 0 & * \\ 0 & 1 & 0 & * \\ 0 & 0 & 1 & * \end{bmatrix}$$

Cannot be a pivot column



Rank

Matrix A is full rank
if $\text{Rank } A = \min(m, n)$

Matrix A is rank deficient
if $\text{Rank } A < \min(m, n)$

- Given a $m \times n$ matrix A:
 - $\text{Rank } A \leq \min(m, n)$
 - Because “the columns of A are independent” is equivalent to “rank $A = n$ ”
 - If $m < n$, the columns of A is dependent.

$$\begin{bmatrix} * & * & * & * \\ * & * & * & * \\ * & * & * & * \end{bmatrix}$$

3 X 4

$\text{Rank } A \leq 3$

$$\left\{ \begin{bmatrix} * \\ * \\ * \end{bmatrix}, \begin{bmatrix} * \\ * \\ * \end{bmatrix}, \begin{bmatrix} * \\ * \\ * \end{bmatrix}, \begin{bmatrix} * \\ * \\ * \end{bmatrix} \right\}$$

A matrix set has 4 vectors
belonging to \mathbb{R}^3 is dependent

In \mathbb{R}^m , you cannot find more than m vectors that are independent.

Consistent or not

$$A: m \times n$$

$$\text{Span}\{a_1, \dots, a_n\} = \mathbb{R}^m = \text{Rank } A = \text{no. of rows}$$

m independent vectors can span \mathbb{R}^m

More than m vectors in \mathbb{R}^m must be dependent.

Theorem 1

A basis is the smallest generation set.

If there is a generation set S for subspace V ,

The size of basis for V is smaller than or equal to S .

Reduction Theorem

There is a basis containing in any generation set S .

S can be reduced to a basis for V by removing some vectors.

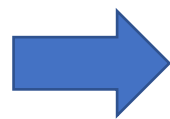
Theorem 1 – Reduction Theorem

所有的 generation set 心中都有一個 basis

S can be reduced to a basis for V by removing some vectors.

Suppose $S = \{\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_k\}$ is a generation set of subspace V

Subspace $V = \text{Span } S$ Let $A = [\mathbf{u}_1 \ \mathbf{u}_2 \ \cdots \ \mathbf{u}_k]$.
 $= \text{Col } A$



The basis of $\text{Col } A$ is
the pivot columns of A Subset of S

Theorem 1 – Reduction Theorem

所有的 generation set 心中都有一個 basis

$$\text{Subspace } V = \text{Span } S = \text{Col } A = \text{Span} \left\{ \begin{bmatrix} 1 \\ -1 \\ 2 \\ -3 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \\ -3 \\ 2 \end{bmatrix}, \begin{bmatrix} 2 \\ 2 \\ 2 \\ 0 \end{bmatrix} \right\}$$

Smallest generation set

$$S = \left\{ \begin{bmatrix} 1 \\ -1 \\ 2 \\ -3 \end{bmatrix}, \begin{bmatrix} 2 \\ -2 \\ 4 \\ 6 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \\ -3 \\ 2 \end{bmatrix}, \begin{bmatrix} 2 \\ 2 \\ 2 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 3 \\ 0 \\ 3 \end{bmatrix}, \begin{bmatrix} 2 \\ 6 \\ 3 \\ 9 \end{bmatrix} \right\}$$

Generation set

$$A = \begin{bmatrix} 1 & 2 & -1 & 2 & 1 & 2 \\ -1 & -2 & 1 & 2 & 3 & 6 \\ 2 & 4 & -3 & 2 & 0 & 3 \\ -3 & -6 & 2 & 0 & 3 & 9 \end{bmatrix} \xrightarrow{\text{RREF}} \begin{bmatrix} 1 & 2 & 0 & 0 & -1 & -5 \\ 0 & 0 & 1 & 0 & 0 & -3 \\ 0 & 0 & 0 & 1 & 1 & 2 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

Theorem 2

A basis is the largest independent set in the subspace.

If the size of basis is k , then you cannot find more than k **independent** vectors in the subspace.

Extension Theorem

Given an independent vector set S in the space

S can be extended to a basis by adding more vectors

Theorem 2 – Extension Theorem

Independent set:

我不是一個 basis 就是正在成為一個 basis

There is a subspace V

Given an independent vector set S (elements of S are in V)

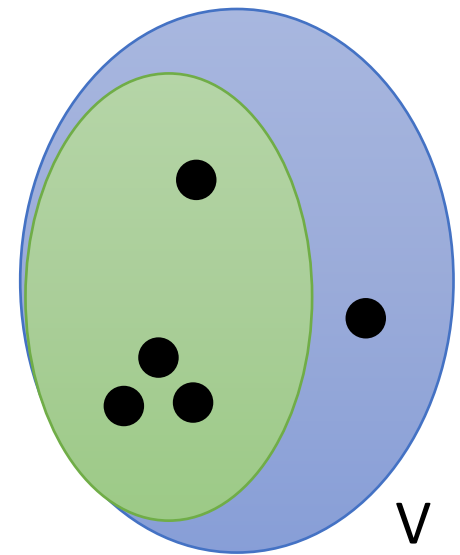
- If $\text{Span } S = V$, then S is a basis
- If $\text{Span } S \neq V$, find v_1 in V , but not in $\text{Span } S$

$S = S \cup \{v_1\}$ is still an independent set

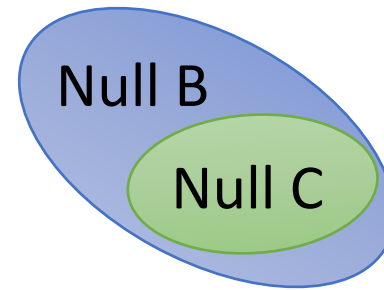
- If $\text{Span } S = V$, then S is a basis
- If $\text{Span } S \neq V$, find v_2 in V , but not in $\text{Span } S$

$S = S \cup \{v_2\}$ is still an independent set

..... You will find the basis in the end.



Theorem 3



- Any two bases of a subspace V contain the same number of vectors

Suppose $\{\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_k\}$ and $\{\mathbf{w}_1, \mathbf{w}_2, \dots, \mathbf{w}_p\}$ are two bases of V .

Let $A = [\mathbf{u}_1 \ \mathbf{u}_2 \ \cdots \ \mathbf{u}_k]$ and $B = [\mathbf{w}_1 \ \mathbf{w}_2 \ \cdots \ \mathbf{w}_p]$.

Since $\{\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_k\}$ spans V , $\exists \mathbf{c}_i \in \mathbb{R}^k$ s.t. $A\mathbf{c}_i = \mathbf{w}_i$ for all i

$$\Rightarrow A[\mathbf{c}_1 \ \mathbf{c}_2 \ \cdots \ \mathbf{c}_p] = [\mathbf{w}_1 \ \mathbf{w}_2 \ \cdots \ \mathbf{w}_p] \Rightarrow AC = B$$

$$\text{Now } C\mathbf{x} = \mathbf{0} \text{ for some } \mathbf{x} \in \mathbb{R}^p \Rightarrow AC\mathbf{x} = B\mathbf{x} = \mathbf{0}$$

B is independent vector set $\Rightarrow \mathbf{x} = \mathbf{0} \Rightarrow \mathbf{c}_1 \ \mathbf{c}_2 \ \cdots \ \mathbf{c}_p$ are independent

$$\mathbf{c}_i \in \mathbb{R}^k \Rightarrow p \leq k$$

Reversing the roles of the two bases one has $k \leq p \Rightarrow p = k$.

Theorem 4.9 (P258)

- If V and W are subspaces of \mathbb{R}^n with V contained in W , then $\dim V \leq \dim W$
- If $\dim V = \dim W$, $V=W$
- Proof:


B_V is a basis of V , V in W , B_V in W

 B_V is an independent set in W

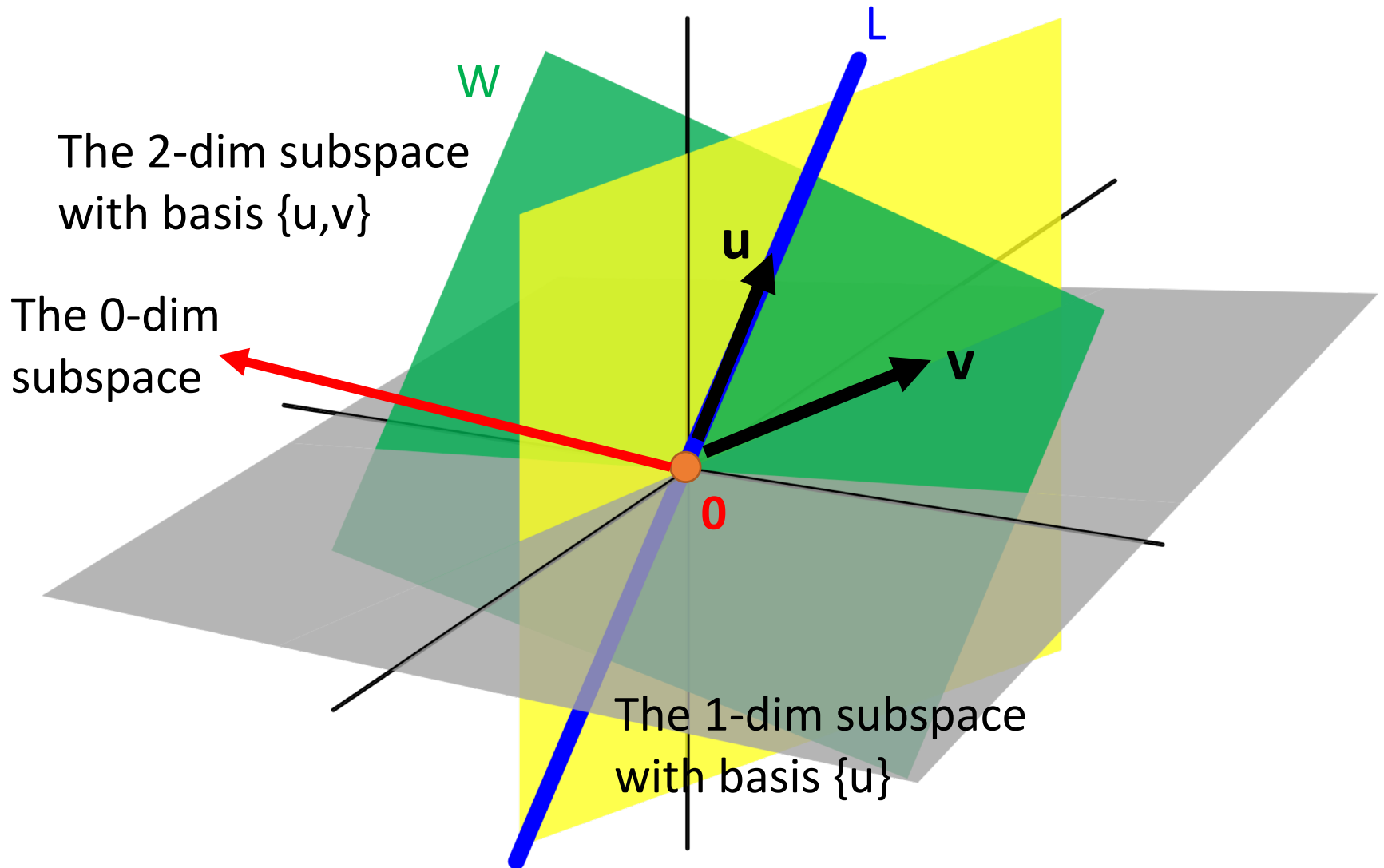
By extension theorem, B_V is in the basis of W  $\dim V \leq \dim W$

If $\dim V = \dim W = k$

B_V is a linear independent set in W , with k elements

 It is also the span of W

\mathbb{R}^3 is the only 3-dim subspace of itself



Concluding Remarks

- 1. A basis is the **smallest** generation set.
- 2. A basis is the **largest** independent vector set in the subspace.
- 3. Any two bases for a subspace **contain the same number of vectors**.
 - The number of vectors in a basis for a nonzero subspace V is called **dimension** of V ($\dim V$).

Concluding Remarks



Generation
set

刪去



Same size



Basis

疊加



Independent
vector set

雕塑 ... 主要是使用雕（通過減除材料來造型）及塑（通過疊加材料來造型）的方式 (from wiki)